



US006934071B2

(12) **United States Patent**
Hunt

(10) **Patent No.:** **US 6,934,071 B2**
(45) **Date of Patent:** **Aug. 23, 2005**

(54) **PIXEL BASED GOBO RECORD CONTROL FORMAT**

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(*) **Notice:** Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 0 days.

(21) **Appl. No.:** **10/271,521**

(22) **Filed:** **Oct. 15, 2002**

(65) **Prior Publication Data**

US 2003/0107795 A1 Jun. 12, 2003

Related U.S. Application Data

(63) Continuation of application No. 09/882,755, filed on Jun. 15, 2001, now Pat. No. 6,466,357, which is a continuation of application No. 09/500,393, filed on Feb. 8, 2000, now Pat. No. 6,256,136, which is a continuation of application No. 09/145,314, filed on Aug. 31, 1998, now Pat. No. 6,057,958.

(60) Provisional application No. 60/059,161, filed on Sep. 17, 1997, and provisional application No. 60/065,133, filed on Nov. 12, 1997.

(51) **Int. Cl.**⁷ **G02B 26/00**; G09G 5/00;
G06T 13/00; G06K 9/00; G06K 9/46

(52) **U.S. Cl.** **359/291**; 359/290; 345/611;
345/473; 345/604; 345/431; 382/167; 382/181;
382/192; 353/122; 362/282

(58) **Field of Search** 382/203, 154,
382/254, 300, 167, 192, 181, 242; 353/25,
122; 358/532, 518; 362/282, 294; 359/290,
291; 345/611, 619, 419, 431, 473, 604,
610

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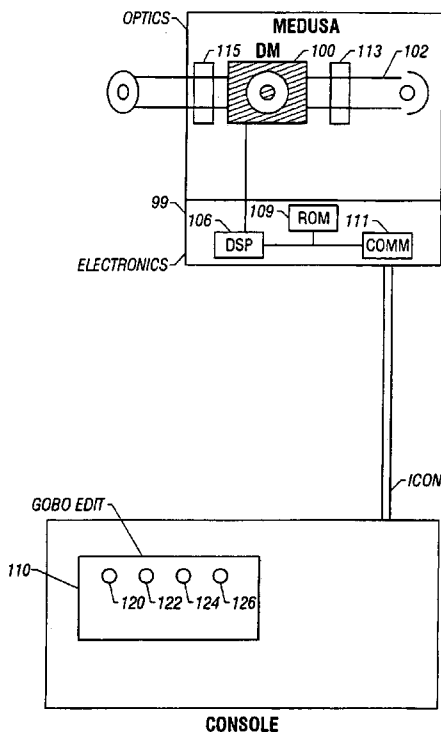
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(57) **ABSTRACT**

A special record format used for commanding light pattern shapes and addressable light pattern shape generator. The command format includes a first part which commands a specified gobo and second parts which command the characteristics of that gobo. The gobo is formed by making a default gobo based on the type and modifying that default gobo to fit the characteristics.

58 Claims, 6 Drawing Sheets



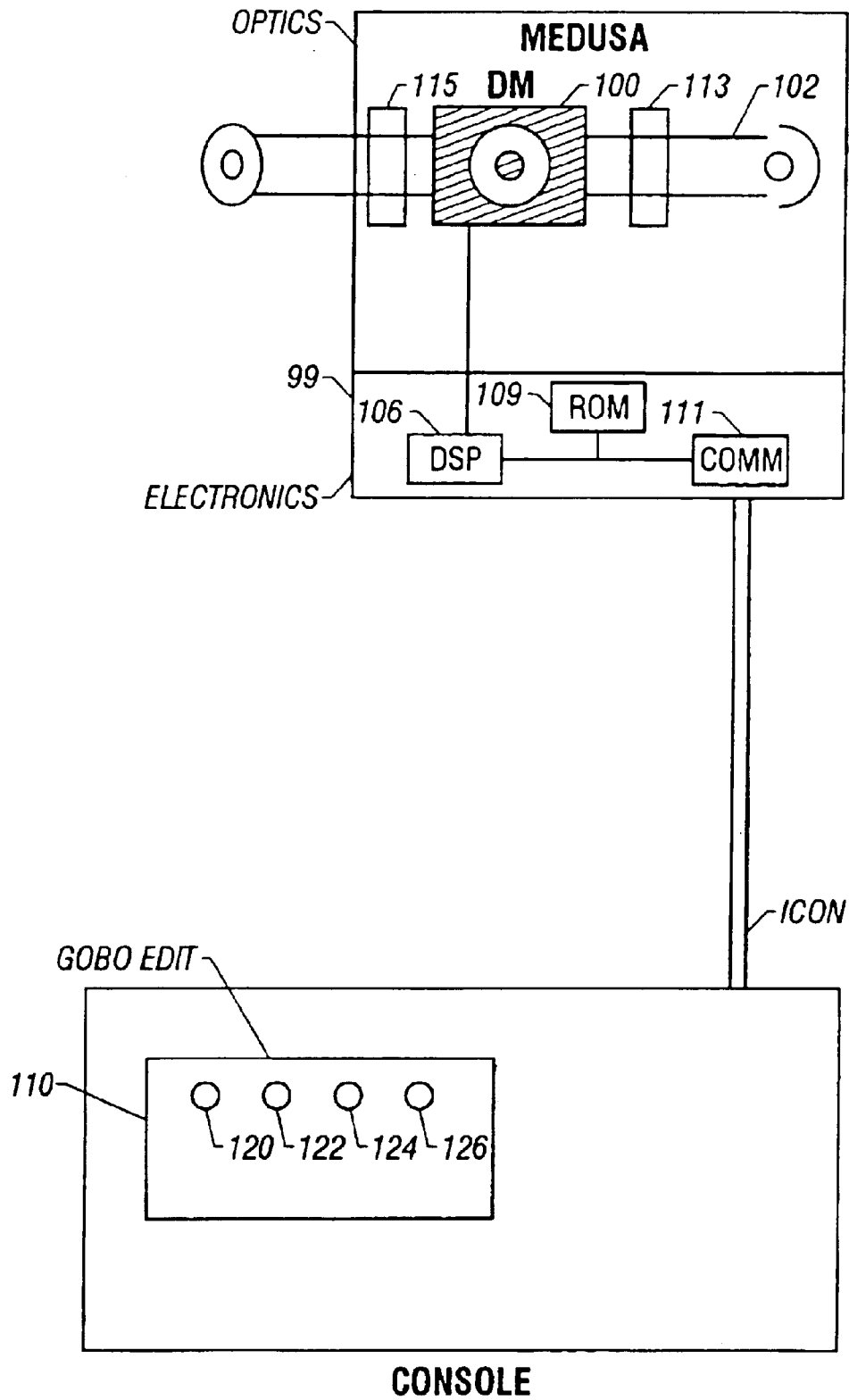


FIG. 1

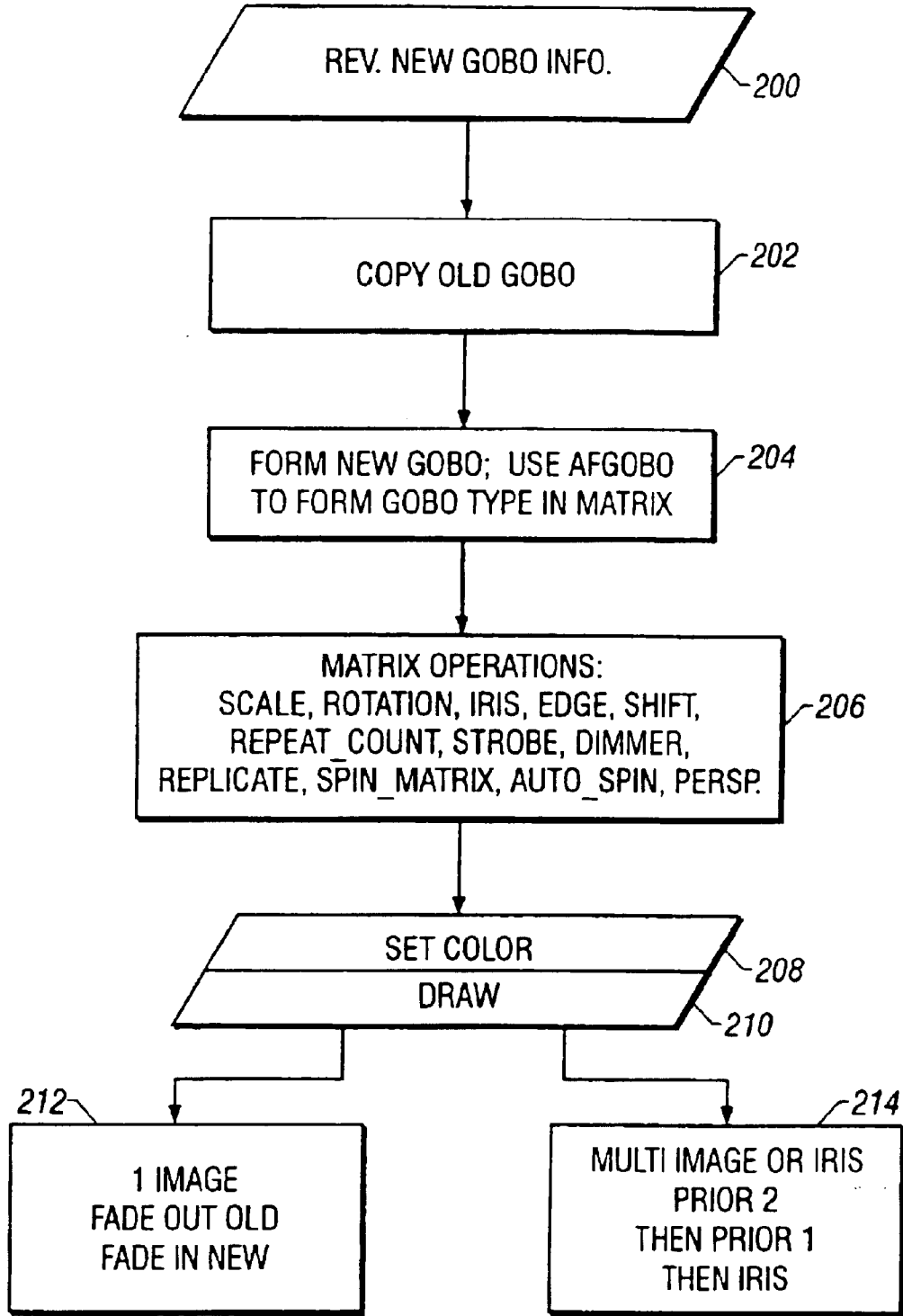


FIG. 2

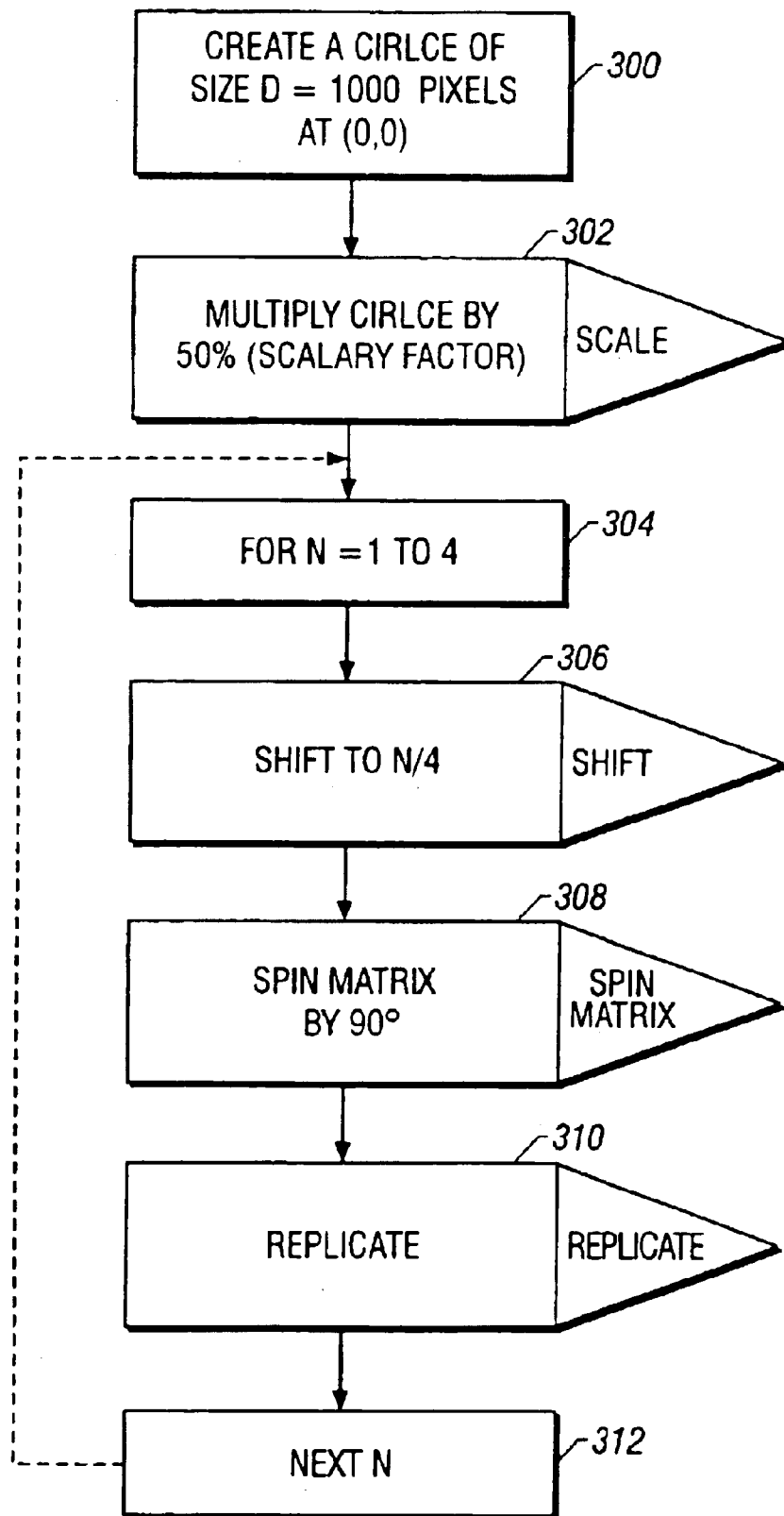


FIG. 3

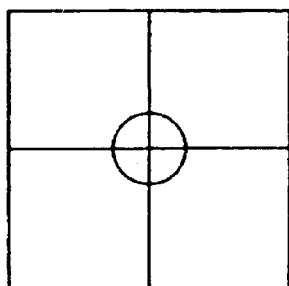


FIG. 4A

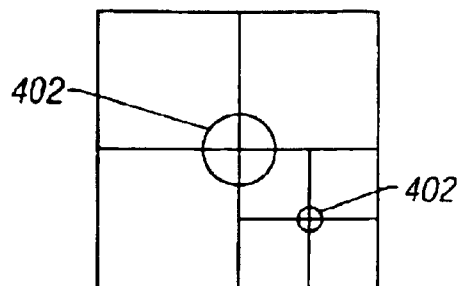


FIG. 4E

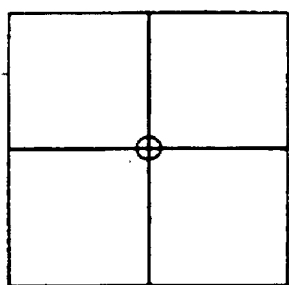


FIG. 4B

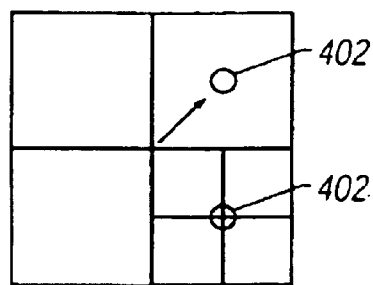


FIG. 4F

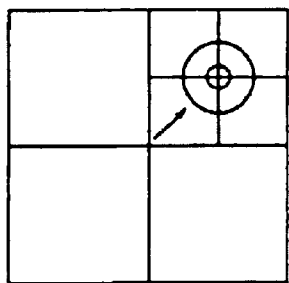


FIG. 4C

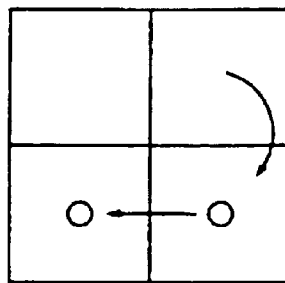


FIG. 4G

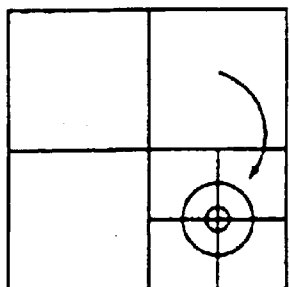


FIG. 4D

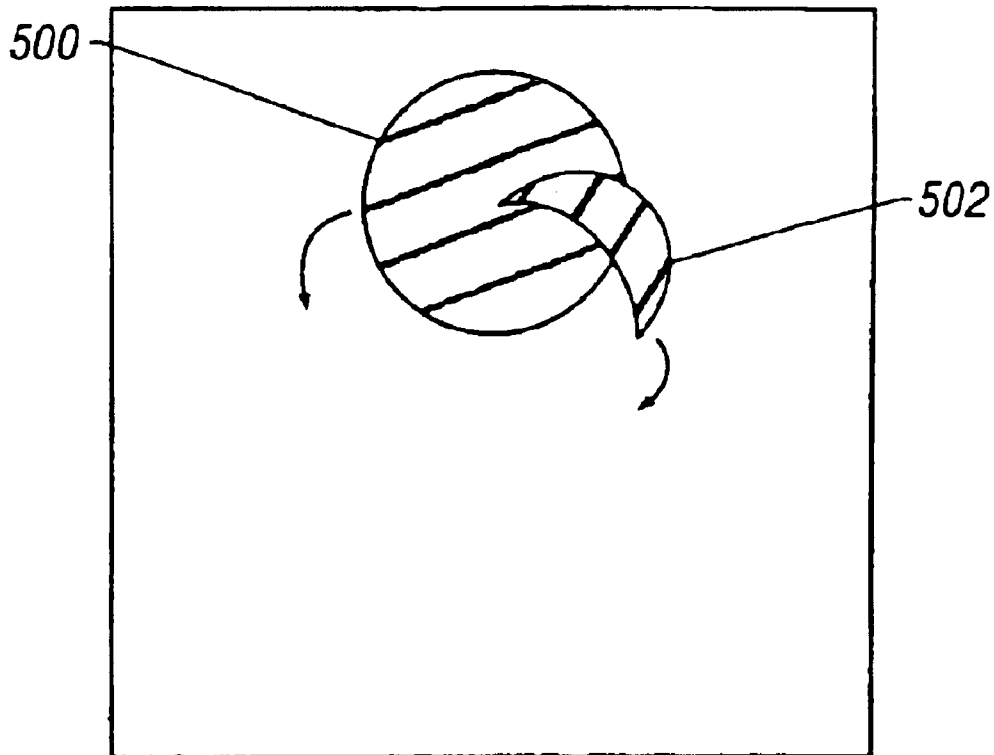


FIG. 5

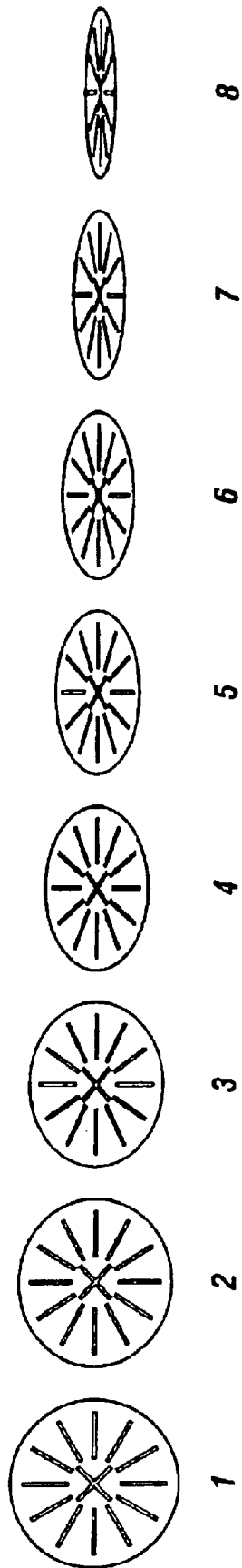


FIG. 6

PIXEL BASED GOBO RECORD CONTROL FORMAT

This application is a continuation of U.S. application Ser. No. 09/882,755, filed Jun. 15, 2001 now U.S. Pat No. 6,466,357, which is a continuation of U.S. application Ser. No. 09/500,393, filed Feb. 8, 2000 now U.S. Pat No. 6,256,136, which is a continuation of U.S. application Ser. No. 09/145,314, filed Aug. 31, 1998 now U.S. Pat No. 6,057,958, which claims priority from U.S. Provisional application Nos. 60/059,161, filed Sep. 17, 1997, and 60/065,133, filed Nov. 12, 1997.

FIELD

The present invention relates to a system of controlling light beam pattern ("gobo") shape in a pixilated gobo control system.

BACKGROUND

Commonly assigned patent application Ser. No. 08/854,353, the disclosure of which is herewith incorporated by reference, describes a stage lighting system which operates based on computer-provided commands to form special effects. One of those effects is control of the shape of a light pattern that is transmitted by the device. This control is carried out on a pixel-by-pixel basis, hence referred to in this specification as pixilated. Control is also carried out using an x-y controllable device. The preferred embodiment describes using a digital mirror device, but other x-y controllable devices such as a grating light valve, are also contemplated.

The computer controlled system includes a digital signal processor **106** which is used to create an image command. That image command controls the pixels of the x-y controllable device to shape the light that it is output from the device.

The system described in the above-referenced application allows unparalleled flexibility in selection of gobo shapes and movement. This opens an entirely new science of controlling gobos. The present inventors found that, unexpectedly, even more flexibility is obtained by a special control language for controlling those movements.

SUMMARY

The present disclosure defines a way of communicating with an x-y controllable device to form special electronic light pattern shapes. More specifically, the present application describes using a control language to communicate with an electronic gobo in order to reposition part or all of the image that is shaping the light.

BRIEF DESCRIPTION OF THE DRAWINGS

These and other aspects of the invention will now be described with reference to the attached drawings, in which:

FIG. 1 shows a block diagram of the basic system operating the embodiment;

FIG. 2 shows a basic flowchart of operation;

FIG. 3 shows a flowchart of forming a replicating circles type gobo;

FIGS. 4A through 4G show respective interim results of carrying out the replicating circles operation;

FIG. 5 shows the result of two overlapping gobos rotating in opposite directions; and

FIGS. 6(1) through 6(8) show a z-axis flipping gobo.

DESCRIPTION OF THE PREFERRED EMBODIMENT

FIG. 1 shows a block diagram of the hardware used according to the preferred embodiment. As described above,

this system uses a digital mirror device **100**, which has also been called a digital mirror device ("DMD") and a digital light processor device ("DLP"). More generally, any system which allows controlling shape of light on a pixel basis, including a grating light valve, could be used as the light shaper. This light shaper forms the shape of light which is transmitted. FIG. 1 shows the light being transmitted as **102**, and shows the transmitted light. The information for the digital mirror **100** is calculated by a digital signal processor **106**. Information is calculated based on local information stored in the lamp, e.g., in ROM **109**, and also in information which is received from the console **104** over the communication link.

The operation is commanded according to a format.

The preferred data format provides 4 bytes for each of color and gobo control information.

The most significant byte of gobo control data, ("dfGobo") indicates the gobo type. Many different gobo types are possible. Once a type is defined, the gobo formed from that type is represented by a number. That type can be edited using a special gobo editor described herein. The gobo editor allows the information to be modified in new ways, and forms new kinds of images and effects.

The images which are used to form the gobos may have variable and/or moving parts. The operator can control certain aspects of these parts from the console via the gobo control information. The type of gobo controls the gobo editor to allow certain parameters to be edited.

The examples given below are only exemplary of the types of gobo shapes that can be controlled, and the controls that are possible when using those gobo shapes. Of course, other controls of other shapes are possible and predictable based on this disclosure.

A first embodiment is the control of an annulus, or "ring" gobo. The DMD **100** in FIG. 1 is shown with the ring gobo being formed on the DMD. The ring gobo is type 000A. When the gobo type 0A is enabled, the gobo editor **110** on the console **104** is enabled and the existing gobo encoders **120**, **122**, **124**, and **126** are used. The gobo editor **110** provides the operator with specialized control over the internal and the external diameters of the annulus, using separate controls in the gobo editor.

The gobo editor and control system also provides other capabilities, including the capability of timed moves between different edited parameters. For example, the ring forming the gobo could be controlled to be thicker. The operation could then effect a timed move between these "preset" ring thicknesses. Control like this cannot even be attempted with conventional fixtures.

Another embodiment is a composite gobo with moving parts. These parts can move through any paths that are programmed in the gobo data itself. This is done in response to the variant fields in the gobo control record, again with timing. Multiple parts can be linked to a single control allowing almost unlimited effects.

Another embodiment of this system adapts the effect for an "eye" gobo, where the pupil of the eye changes its position (look left, look right) in response to the control.

Yet another example is a Polygon record which can be used for forming a triangle or some other polygonal shape.

The control can be likened to the slider control under a QuickTime movie window, which allows you to manually move to any point in the movie. However, our controls need not be restricted to timelines.

Even though such moving parts are used, scaling and rotation on the gobo is also possible.

The following type assignments are contemplated:
 00-0F=FixedGobo (with no "moving parts")
 10-1F=SingleCntrl (with 1 "moving part")
 20-2F=DoubleCntrl (with 2 "moving parts")
 30-FF=undefined, reserved.

The remaining control record bytes for each type are defined as follows:

Byte: memory	dfGobo2	dfGobo3	dfGobo4	#gobos/type,	total
- FixedGobo:	ID [23:16]	ID [15:8]	ID [7:0]	16M/type	256M
SingleCntrl:	ID [15:8]	ID [7:0]	control#1	64k/type	1M
DoubleCntrl:	ID [7:0]	control#2	control#1	256/type	4k

As can be seen from this example, this use of the control record to carry control values does restrict the number of gobos which can be defined of that type, especially for the 2-control type.

Console Support:

The use of variant part gobos requires no modifications to existing console software for the ICON (7M) console. The Gobo editor in current ICON software already provides 4 separate encoders for each gobo. These translate directly to the values of the 4 bytes sent in the communications data packet as follows:

Byte: dfGobo	dfGobo2	dfGobo3	dfGobo4
Enc: TopRight	MidRight	BotRight	BotLeft
FixedGobo:	ID [23:16]	ID [15:8]	ID [7:0]
SingleCntrl:	ID [15:8]	ID [7 0]	control#1
DoubleCntrl:	ID [7:0]	control#2	control#1

These values would be part of a preset gobo, which could be copied as the starting point.

Once these values are set, the third and fourth channels automatically become the inner/outer radius controls. Using two radii allows the annulus to be turned "inside out".

Each control channel's data always has the same meaning within the console. The console treats these values as simply numbers that are passed on. The meanings of those numbers, as interpreted by the lamps change according to the value in dfGobo.

The lamp will always receives all 4 bytes of the gobo data in the same packet. Therefore, a "DoubleCntrl" gobo will always have the correct control values packed along with it.

Hence, the console needs no real modification. If a "soft" console is used, then name reassignments and/or key reassignments may be desirable.

Timing:

For each data packet, there is an associated "Time" for gobo response. This is conventionally taken as the time allotted to place the new gobo in the light gate. This delay has been caused by motor timing. In this system, variant gobo, the control is more dynamically used. If the non-variant parts of the gobo remain the same, then it is still the same gobo, only with control changes. Then, the time value is interpreted as the time allowed for the control change.

Since different gobo presets (in the console) can reference the same gobo, but with different control settings, this allows easily programmed timed moves between different annuli, etc.

Internal Workings:

When the gobo command data is extracted from the packet at the lamp, the dfGobo byte is inspected first, to see

if either dfGobo3 or dfGobo4 are significant in selecting the image. In the case of the "Cntrl" variants, one or both of these bytes is masked out, and the resulting 32-bit number is used to search for a matching gobo image (by Gobo_ID) in the library stored in the lamp's ROM 109.

If a matching image is found, and the image is not already in use, then the following steps are taken:

1) The image data is copied into RAM, so that its fields may be modified by the control values. This step will be skipped if the image is currently active.

2) The initial control values are then recovered from the data packet, and used to modify certain fields of the image data, according to the control records.

3) The image is drawn on the display device, using the newly-modified fields in the image data.

If the image is already in use, then the RAM copy is not altered. Instead, a time-sliced task is set up to slew from the existing control values to those in the new data packet, in a time determined by the new data packet.

At each vertical retrace of the display, new control values are computed, and steps 2 (using the new control values) and 3 above are repeated, so that the image appears modified with time.

The image data records:

All images stored in the lamp are in a variant record format: Header:

Length 32 bits, offset to next gobo in list.

Gobo_ID 32 bits, serial number of gobo.

Gobo records:

Length	32 bits, offset to next record.
Opcode	16 bits, type of object to be drawn.
Data	Variant part-data describing object.
_Length	32 bits, offset to next record.
Opcode	16 bits, type of object to be drawn.
Data	Variant part-data describing object.
_ EndMarker	64 bits, all zeroes-indicates end of gobo data.
+ Next gobo,	or End Marker, indicating end of gobo list.

Gobos with controls are exactly the same, except that they contain control records, which describe how the control values are to affect the gobo data. Each control record contains the usual length and Opcode fields, and a field containing the control number (1 or 2).

These are followed by a list of "field modification" records. Each record contains information about the offset (from the start of the gobo data) of the field, the size (8, 16 or 32 bits) of the field, and how its value depends on the control value.

Length	32 bits, offset to next record
Opcode	16 bits = control_record (constant)
CntrlNum	16 bits = 1 or 2 (control number) /* field modification record #1 */
Address	16 bits, offset from start of gobo to affected field.
Flags	16 bits, information about field (size, signed, etc)
Scale use	16 bits, scale factor applied to control before use
ZPoint	16 bits, added to control value after scaling. /* field modification record #2 */
Address	16 bits, offset from start of gobo to affected field.
Flags	16 bits, information about field (size, signed, etc)
Scale use	16 bits, scale factor applied to control before use
ZPoint	16 bits, added to control value after scaling.

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As can be seen, a single control can have almost unlimited effects on the gobo, since ANY values in the data can be modified in any way, and the number of field modification records is almost unlimited.

Note that since the control records are part of the gobo data itself, they can have intimate knowledge of the gobo structure. This makes the hard-coding of field offsets acceptable.

In cases where the power offered by this simple structure is not sufficient, a control record could be defined which contains code to be executed by the processor. This code would be passed parameters, such as the address of the gobo data, and the value of the control being adjusted.

Example Records.

The Annulus record has the following format:

Length	32 bits
Opcode	16 bits, = type__annulus
Pad	16 bits, unused
Centre_x	16 bits, x coordinate of centre
Centre_y	16 bits, y coordinate of centre
OuterRad	16 bits, outside radius (the radii get swapped when drawn if their values are in the wrong order)
InnerRad	16 bits, inside radius

It can be seen from this that it is easy to "target" one of the radius parameters from a control record. Use of two control records, each with one of the radii as a target, would provide full control over the annulus shape.

Note that if the centre point coordinates are modified, the annulus will move around the display area, independent of any other drawing elements in the same gobo's data.

The Polygon record for a triangle has this format:

Length	32 bits
Opcode	16 bits, = type__polygon
Pad	16 bits, vertex count = 3
Centre_x	16 bits, x coordinate of vertex
Centre_y	16 bits, y coordinate of vertex
Centre_x	16 bits, x coordinate of vertex
Centre_y	16 bits, y coordinate of vertex
Centre_x	16 bits, x coordinate of vertex
Centre_y	16 bits, y coordinate of vertex

It is easy to modify any of the vertex coordinates, producing distortion of the triangle.

The gobo data can contain commands to modify the drawing environment, by rotation, scaling, offset, and color control, the power of the control records is limitless.

Second Embodiment

This second embodiment provides further detail about implementation once the gobo information is received.

Gobo information is, at times, being continuously calculated by DSP 106. The flowchart of FIG. 2 shows the handling operation that is carried out when new gobo information is received.

At step 200, the system receives new gobo information. In the preferred embodiment, this is done by using a communications device 111 in the lamp 99. The communications device is a mailbox which indicates when new mail is received. Hence, the new gobo information is received at step 200 by determining that new mail has been received.

At step 202, the system copies the old gobo and switches pointers. The operation continues using the old gobo until the draw routine is called later on.

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At step 204, the new information is used to form a new gobo. The system uses a defined gobo ("dfGobo") as discussed previously which has a defined matrix. The type dfGobo is used to read the contents from the memory 109 and thereby form a default image. That default image is formed in a matrix. For example, in the case of an annulus, a default size annulus can be formed at position 0,0 in the matrix. An example of forming filled balls is provided herein.

Step 206 represents calls to subroutines. The default gobo is in the matrix, but the power of this system is its ability to very easily change the characteristics of that default gobo. In this embodiment, the characteristics are changed by changing the characteristics of the matrix and hence, shifting that default gobo in different ways. The matrix operations, which are described in further detail herein, include scaling the gobo, rotation, iris, edge, strobe, and dimmer. Other matrix operations are possible. Each of these matrix operations takes the default gobo, and does something to it.

For example, scale changes the size of the default gobo rotation rotates the default gobo by a certain amount.

Iris simulates an iris operation by choosing an area of interest, typically circular, and erasing everything outside that area of interest. This is very easily done in the matrix, since it simply defines a portion in the matrix where all black is written.

Edge effects carry out certain effects on the edge such as softening the edge. This determines a predetermined thickness, which is translated to a predetermined number of pixels, and carries out a predetermined operation on the number of pixels. For example, for a 50% edge softening, every other pixel can be turned off. The strobe is in effect that allows all pixels to be turned on and off at a predetermined frequency, i.e., 3 to 10 times a second. The dimmer allows the image to be made dimmer by turning off some of the pixels at predetermined times.

The replicate command forms another default gobo, to allow two different gobos to be handled by the same record. This will be shown with reference to the exemplary third embodiment showing balls. Each of those gobos is then handled as the same unit and the entirety of the gobos can be, for example, rotated. The result of step 206 and all of these subroutines that are called is that the matrix includes information about the bits to be mapped to the digital mirror 100.

At step 208, the system then obtains the color of the gobos from the control record discussed previously. This gobo color is used to set the appropriate color changing circuitry 113 and 115 in the lamp 99. Note that the color changing circuitry is shown both before and after the digital mirror 100. It should be understood that either of those color changing circuits could be used by itself.

At step 210, the system calls the draw routine in which the matrix is mapped to the digital mirror. This is done in different ways depending on the number of images being used. Step 212 shows the draw routine for a single image being used as the gobo. In that case, the old gobo, now copied as shown in step 202, is faded out while the new gobo newly calculated is faded in. Pointers are again changed so that the system points to the new gobo. Hence, this has the effect of automatically fading out the old gobo and fading in the new gobo.

Step 214 schematically shows the draw routine for a system with multiple images for an iris. In that system, one of the gobos is given priority over the other. If one is brighter than the other, then that one is automatically given priority.

The one with priority 2, the lower priority one, is written first. Then the higher priority gobo is written. Finally, the iris is written which is essentially drawing black around the edges of the screen defined by the iris. Note that unlike a conventional iris, this iris can take on many different shapes. The iris can take on not just a circular shape, but also an elliptical shape, a rectangular shape, or a polygonal shape. In addition, the iris can rotate when it is non-circular so that for the example of a square iris, the edges of the square can actually rotate.

Returning to step 206, in the case of a replicate, there are multiple gobos in the matrix. This allows the option of spinning the entire matrix, shown as spin matrix.

An example will now be described with reference to the case of repeating circles. At step 200, the new gobo information is received indicating a circle. This is followed by the other steps of 202 where the old gobo is copied, and 204 where the new gobo is formed. The specific operation forms a new gobo at step 300 by creating a circle of size diameter equals 1000 pixels at origin 00. This default circle is automatically created. FIG. 4A shows the default gobo which is created, a default size circle at 00. It is assumed for purposes of this operation that all of the circles will be the same size.

At step 302, the circle is scaled by multiplying the entire circle by an appropriate scaling factor. Here, for simplicity, we are assuming a scaling factor of 50% to create a smaller circle. The result is shown in FIG. 4B. A gobo half the size of the gobo of FIG. 4A is still at the origin. This is actually the scale of the subroutine as shown in the right portion of step 302. Next, since there will be four repeated gobos in this example, a four-loop is formed to form each of the gobos at step 304. Each of the gobos is shifted in position by calling the matrix operator shift. In this example, the gobo is shifted to a quadrant to the upper right of the origin. This position is referred to as π over 4 in the FIG. 3 flowchart and results in the gobo being shifted to the center portion of the top right quadrant as shown in FIG. 4C. This is again easily accomplished within the matrix by moving the appropriate values. At step 308, the matrix is spun by 90 degrees in order to put the gobo in the next quadrant as shown in FIG. 4D in preparation for the new gobo being formed into the same quadrant. Now the system is ready for the next gobo, thereby calling the replicate command which quite easily creates another default gobo circle and scales it. The four-loop is then continued at step 312.

The replicate process is shown in FIG. 4E where a new gobo 402 is formed in addition to the existing gobo 400. The system then passes again through the four-loop, with the results being shown in the following figures. In FIG. 4F, the new gobo 402 is again moved to the upper right quadrant (step 306). In FIG. 4G, the matrix is again rotated to leave room for a new gobo in the upper right quadrant. This continues until the end of the four-loop. Hence, this allows each of the gobos to be formed.

Since all of this is done in matrix operation, it is easily programmable into the digital signal processor. While the above has given the example of a circle, it should be understood that this scaling and moving operation can be carried out for anything. The polygons, circles, annulus, and everything else is easily scaled.

The same operation can be carried out with the multiple parameter gobos. For example, for the case of a ring, the variable takes the form annulus (inner R, outer R, x and y). This defines the annulus and turns of the inner radius, the outer radius, and x and y offsets from the origin. Again, as

shown in step 3, the annulus is first written into the matrix as a default size, and then appropriately scaled and shifted. In terms of the previously described control, the ring gobo has two controls: control 1 and control 2 defined the inner and outer radius.

Each of these operations is also automatically carried out by the command repeat count which allows easily forming the multiple position gobo of FIGS. 4A-4G. The variable auto spin defines a continuous spin operation. The spin operation commands the digital signal processor to continuously spin the entire matrix by a certain amount each time.

One particularly interesting feature available from the digital mirror device is the ability to use multiple gobos which can operate totally separately from one another raises the ability to have different gobos spinning in different directions. When the gobos overlap, the processor can also calculate relative brightness of the two gobos. In addition, one gobo can be brighter than the other. This raises the possibility of a system such as shown in FIG. 5. Two gobos are shown spinning in opposite directions: the circle gobo 500 is spinning the counterclockwise direction, while the half moon gobo 502 is spinning in the clockwise direction. At the overlap, the half moon gobo which is brighter than the circle gobo, is visible over the circle gobo. Such effects were simply not possible with previous systems. Any matrix operation is possible, and only a few of those matrix operations have been described herein.

A final matrix operation to be described is the perspective transformation. This defines rotation of the gobo in the Z axis and hence allows adding depth and perspective to the gobo. For each gobo for which rotation is desired, a calculation is preferably made in advance as to what the gobo will look like during the Z axis transformation. For example, when the gobo is flipping in the Z axis, the top goes back and looks smaller while the front comes forward and looks larger. FIGS. 6(1)-6(8) show the varying stages of the gobo flipping. In FIG. 6(8), the gobo has its edge toward the user. This is shown in FIG. 6(8) as a very thin line, e.g., three pixels wide, although the gobo could be zero thickness at this point. Automatic algorithms are available for such Z axis transformation, or alternatively a specific Z axis transformation can be drawn and digitized automatically to enable a custom look.

Although only a few embodiments have been described in detail above, other embodiments are contemplated by the inventor and are intended to be encompassed within the following claims. In addition, other modifications are contemplated and are also intended to be covered.

What is claimed is:

1. A computer system comprising:
 - a computer based controller producing an output signal that includes parameters that digitally control a shape of a projected light.
 2. A system as in claim 1, wherein said computer based controller includes a memory storing associated information about shapes for said output signal.
 3. A system as in claim 1, wherein said output signal is in a specified format, where different parts of the signal have different information to control said shape.
 4. A system as in claim 3, wherein said format includes a part which controls a specific color of said projected light.
 5. A computer system comprising:
 - a computer based controller producing an output signal that includes parameters that digitally control a shape of a projected light, wherein said output signal includes a first part which represents a specific shape which is projected.

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6. A system as in claim 5, wherein said first part includes a number representing a prestored shape.

7. A system as in claim 5, wherein said first part includes information indicative of a basic shape, and information indicative of modifications to said basic shape.

8. A system as in claim 7, wherein said information indicative of said basic shape is a number representing a prestored shape.

9. A system as in claim 5, wherein said output signal also includes a second part which controls a specific color of said projected light.

10. A computer system comprising:

a computer based controller producing an output signal that includes parameters that digitally control a shape of a projected light; and an input to said computer based controller which allows an operator to control aspects of said shape.

11. A system as in claim 10, wherein said input allow the operator to select one of a plurality of different shapes.

12. A system as in claim 11, wherein said input further allows the operator to modify said one of said plurality of different shapes.

13. A system as in claim 12, wherein said user interface allows selecting one of a plurality of prestored shapes.

14. A system as in claim 13, wherein said user interface allows modifying said one of said prestored shapes.

15. A computer system comprising:

a computer based controller producing an output signal that includes parameters that digitally control a shape of a projected light; and a user interface, associated with said computer based controller, which user interface allows selecting said shapes.

16. A system, comprising:

a computer based controller which produces an output signal that allows digitally controlling at least a shape of a projected light, said output signal including information indicative of a basic shape of the projected light, and modifications to the basic shape.

17. A system as in claim 16, wherein said information indicative of the basic shape comprises a designation that represents the basic shape.

18. A system as in claim 16, wherein said information indicative of the basic shape is information that is indicative of a specified shape of unit size.

19. A system, comprising:

a computer based controller, including a user interface which allows designating a shape, and a controller which produces an output signal which is adapted to control a digital light to produce output light having the designated shape, wherein said output signal includes control information indicative of the designated shape, said control information including information indicative of a prestored shape.

20. A system as in claim 19, wherein said information indicative of the prestored shape comprises a designation which represents a specified unit shape.

21. A system as in claim 19, wherein said control information further includes information indicative of modification of said basic shape.

22. A system as in claim 19, wherein said output signal is a signal that is adapted to control a lighting device including a digital mirror device.

23. A system, comprising:

a user interface;

a computer based controller which is coupled to said user interface, and receives commands from said user

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interface, said commands including commands indicative of a shape of light to be projected, and said controller producing an output signal indicative of said commands.

24. A system as in claim 23, wherein said computer based controller further comprises a memory storing a plurality of different shapes for said light to be projected, each of said shapes including a designation associated therewith, and wherein said commands include information indicative of at least one of said designations.

25. A system as in claim 24, wherein said output signal also includes designations indicative of prestored shapes in an object being controlled by said output signal.

26. A system as in claim 24, further comprising at least one remote light, said light including a digital micromirror device therein enabling projection of light having a pre specified shape, and wherein the remote light includes shapes stored therein, and said commands include the designations indicative of at least one of said shapes.

27. A system as in claim 23, wherein said commands from said user interface also include a color of light to be projected, and said output signal includes light to be projected.

28. A system, comprising:

a computer based controller producing an output signal with a gobo control record therein, said gobo control record being a digital signal that specifies control of at least a shape and movement of an electronically-produced gobo.

29. A system as in claim 28, wherein the gobo control record includes a field representing a color of a part of the gobo part.

30. A system as in claim 28, wherein the gobo control record includes a field representing a type of the gobo being controlled.

31. A system, comprising:

a computer based controller producing an output signal with a gobo control record therein, said gobo control record being a digital signal that specifies control of at least a shape and movement of an electronically-produced gobo, wherein said gobo control records include a plurality of fields including at least shape of the gobo, movement of the gobo, and timing of the gobo.

32. A system, comprising:

a computer based controller producing an output signal with a gobo control record therein, said gobo control record being a digital signal that specifies control of at least a shape and movement of an electronically-produced gobo, wherein the gobo control record includes a field representing a thickness of a part of said gobo.

33. A system, comprising:

a computer based controller producing an output signal with a gobo control record therein, said gobo control record being a digital signal that specifies control of at least a shape and movement of an electronically-produced gobo, wherein the gobo control record includes a field representing a size of a part of the gobo.

34. A system, comprising:

a computer based controller producing an output signal with a gobo control record therein, said gobo control record being a digital signal that specifies control of at least a shape and movement of an electronically-produced gobo, wherein the gobo control record includes a field representing a position of a part of the gobo.

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- 35. A system, comprising:
a computer based controller producing an output signal with a gobo control record therein, said gobo control record being a digital signal that specifies control of at least a shape and movement of an electronically-produced gobo, wherein the gobo record includes a field representing a type of the gobo being controlled, and wherein said type represents different ways that the gobo can be controlled.
- 36. A system as in claim 35, wherein said different ways include no moving parts or moving part.
- 37. A system as in claim 35, wherein said different ways include no moving parts or moving parts.
- 38. A system, comprising:
a computer based controller producing an output signal with a gobo control record therein, said gobo control record being a digital signal that specifies control of at least a shape and movement of an electronically-produced gobo, wherein the gobo record includes a field representing a type of the gobo being controlled, and wherein said type represents whether or not the gobo can be controlled.
- 39. A system, comprising:
a computer based controller producing an output signal with a gobo control record therein, said gobo control record including a gobo type which specifies the kinds of control to the gobo that can be represented by the record.
- 40. A system as in claim 39, wherein the gobo control record includes a field representing a thickness of a part of the gobo.
- 41. A system as in claim 39, wherein the gobo control record includes a field representing a size of a part of the gobo.
- 42. A system as in claim 39, wherein the gobo control record includes a field representing a position of a part of the gobo.
- 43. A system as in claim 39, wherein the gobo control record includes a field representing a color of a part of the gobo.
- 44. A system as in claim 39, wherein the gobo record includes a field representing a type of the gobo being controlled.
- 45. A system as in claim 44, wherein said type represents the different ways that the gobo can be controlled.
- 46. A system as in claim 44, wherein said type represents whether or not the gobo can be controlled.
- 47. A controller, comprising:
a controlling part which allows selecting one of a plurality of different gobo types to be controlled; and

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- a plurality of controlling encoders, associated with said controlling part, at least one of which encoders is assigned to control different values, depending on the gobo type being controlled.
- 48. A controller as in claim 47, further comprising a processor, which produces an output signal based on settings of said controlling part and said controlling encoders.
- 49. A controller as in claim 48, wherein said output signal represents a shape of light to be projected by a remote fixture.
- 50. A controller as in claim 48, wherein said output signal includes a first field for a control type, and for at least one of said controlled types, another field for information indicative of control variables.
- 51. A controller as in claim 47, wherein said controlling encoders control at least a time for gobo response.
- 52. A controller, comprising:
a controlling part which allows selecting one of a plurality of different gobos;
a console, with a plurality of controls, on said console, which are capable of being dynamically assigned, and
a processor, which determines said one of said plurality of different gobos, the values associated with said one of said plurality of different gobos, and assigns said plurality of controls based on the one of the plurality of different gobos which is selected.
- 53. A controller as in claim 52, wherein said plurality of controls include at least an encoder.
- 54. A controller as in claim 53, wherein said processor also produces an output signal that commands controlling the shape of projected light of a remote lighting fixture.
- 55. A controller, comprising:
a computer based controller producing an output signal that has a first part that commands a shape of a projected light and a second part that controls a time associated with said shape.
- 56. A controller as in claim 55, wherein said output signal commands changing between a first shape and a second shape, and said time represents a time to change from said first shape to said second shape.
- 57. A controller as in claim 55, wherein said output signal represents a control change, and said time represents a time that is allowed for the control change.
- 58. A controller as in claim 55, wherein said output signal represents the same gobo with different settings, and said time represents a time for move between the settings.

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